

# Small Computer System Interface

- Part 1



[forensic-proof.com](http://forensic-proof.com)

proneer

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# Outline

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## 1. *SCSI Basics (geeks.com, tech-tips)*

- ✓ *The Basics*
- ✓ *Performance*
- ✓ *Price*
- ✓ *Reliability*

## 2. *More than an interface – SCSI vs. ATA (March 2003)*

- ✓ *Introduction*
- ✓ *Technology Differences*
- ✓ *Performance Differences*
- ✓ *Conclusions*

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# SCSI Basics

*COMPUTER GEEKS (geeks.com), tech-tips HARDWARE*

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# SCSI Basics

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## • The Basics

- ✓ Small Computer System Interface(SCSI), ATA → first introduced in 1986
- ✓ "skuzzy"
- ✓ "host adaptor"(adaptor card), connecting SCSI drives to the motherboard

# SCSI Basics

## • The Basics – On board vs. Adaptor card



On board SATA Connector



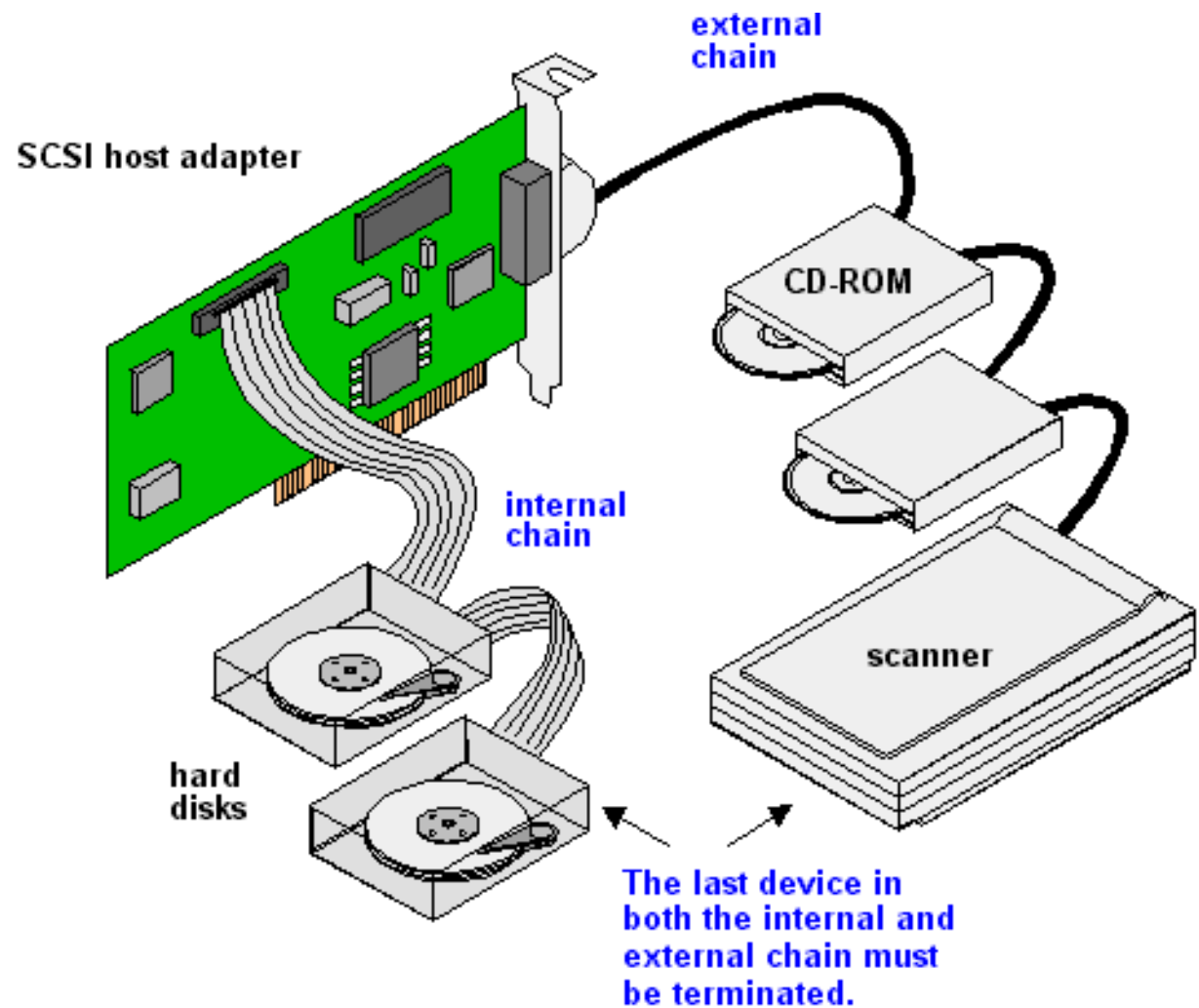
SCSI Adaptor card

- ✓ On board 40-pin ATA connector & 7-pin SATA connector
- ✓ PCI or PCI-X slots, SCSI 25, 50, 68, 80-pin
- ✓ SCSI drives can communicate directly, requiring almost no CPU support

# SCSI Basics

## • The Basics – The cables

- ✓ ATA - Max 2 devices
- ✓ SATA - Max 1 device
- ✓ SCSI
  - daisy chain
  - Max 16 devices



# SCSI Basics

- The Basics – The cables

```
Adaptec AHA-2940 Ultra/Ultra W ◀ SCSISelect(TM) ▶ Utility v1.34.3
AHA-2940 Ultra/Ultra W at Bus:00h Device:00h

Select SCSI Disk and press <Enter>

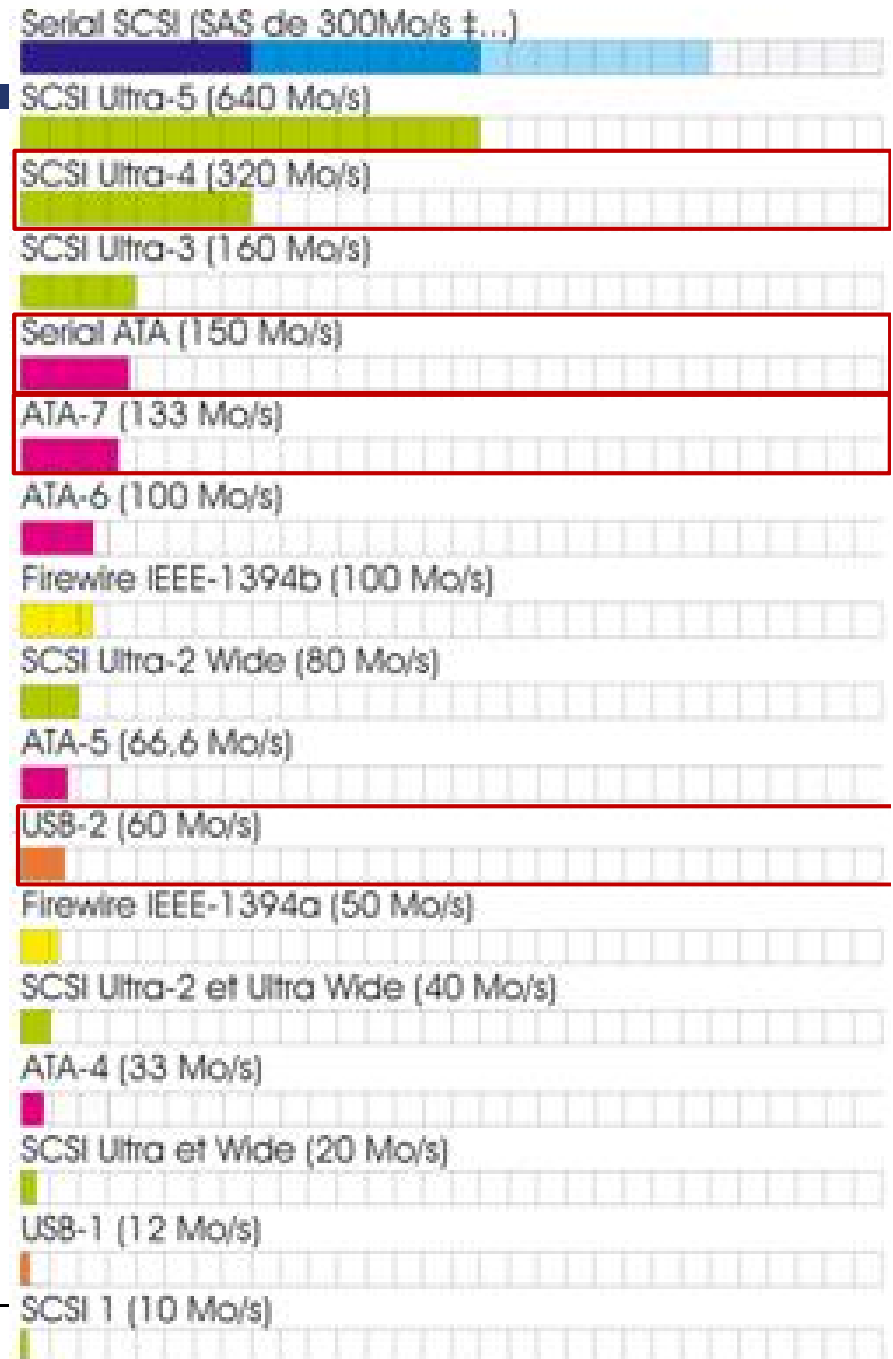
SCSI ID #0:      No device
SCSI ID #1:      No device
SCSI ID #2:      No device
SCSI ID #3:      IBM          DCAS-34330W
SCSI ID #4:      No device
SCSI ID #5:      No device
SCSI ID #6:      ARCHIVE  Python 20049-XXX
SCSI ID #7:      AHA-2940 Ultra/Ultra W
SCSI ID #8:      No device
SCSI ID #9:      No device
SCSI ID #10:     No device
SCSI ID #11:     No device
SCSI ID #12:     No device
SCSI ID #13:     No device
SCSI ID #14:     No device
SCSI ID #15:     No device

Arrow keys to move cursor, <Enter> to select option, <Esc> to exit (*-default)
```

# SCSI Basics

## • The Basics – Performance

- ✓ SCSI 1 – 5 MBps | 8 bit wide (5 MHz)
  - 8 devices per 1 controller channel
  
- ✓ Ultra320 SCSI – 320 MBps | 16 bit wide (40 MHz)
  - 16 devices per 1 controller channel





# SCSI Basics

## • The Basics – Performance SCSI vs. ATA

	Transfer speed (MB/s)	Max. cable length (m)	maximum connecting devices
SCSI 1	5	-	8
Ultra 320 SCSI	320	12	15 (plus the HBA; Host Bus Adaptor)
PATA-133	133	0.46	2
SATA-150 (SATA I)	150	1	1
SATA-300 (SATA II)	300	1	1

# SCSI Basics

## • The Basics – Prices

	Disk size (GB)	RPMs	Prices (WON)
Ultra 320 SCSI	146	15,000	326,100
	300	10,000	630,000
SAS	300	15,000	514,000
EIDE(ATA-133)	320	7,200	74,000
SATA2(SATA-300)	320	7,200	54,700

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# SCSI Basics

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## • The Basics – Reliability

- ✓ One of the key reason for **SCSI's higher price is reliability**
- ✓ **SCSI drives are built to a much higher standard** than typical ATA or SATA drives
- ✓ Mean Time Between Failure(MTBF)
  - 1.5 million hour on SCSI
  - 1 million hour on SATA or less
- ✓ Operation Uptime
  - SCSI - 24/7
  - ATA or SATA - 8 hours per day

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# More than an interface – SCSI vs. ATA

*2<sup>nd</sup> Annual Conference on File and Storage Technology (FAST), 2003*

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# Introduction

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## • Categorize

### ✓ Personal Storage

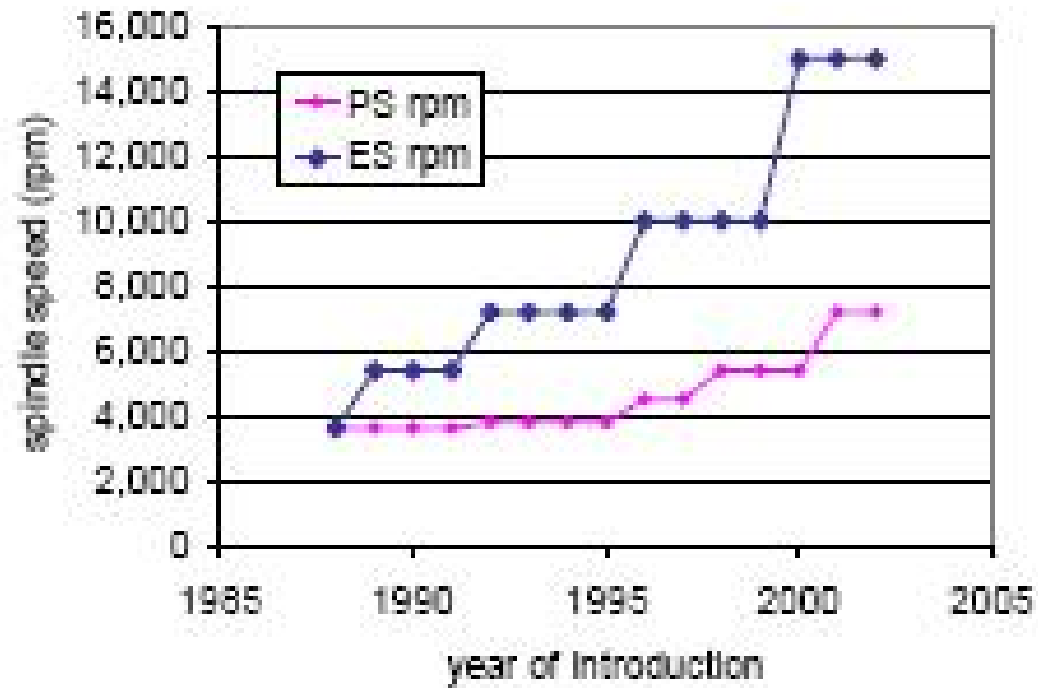
- **personal computer market** uses to the first low-cost hard discs

### ✓ Enterprise Storage

- **To be configured in groups** (aggregation)
- **To randomly access** small portions of large data spaces
- **reliability and performance** are critical characteristics

# Introduction

## • RPM



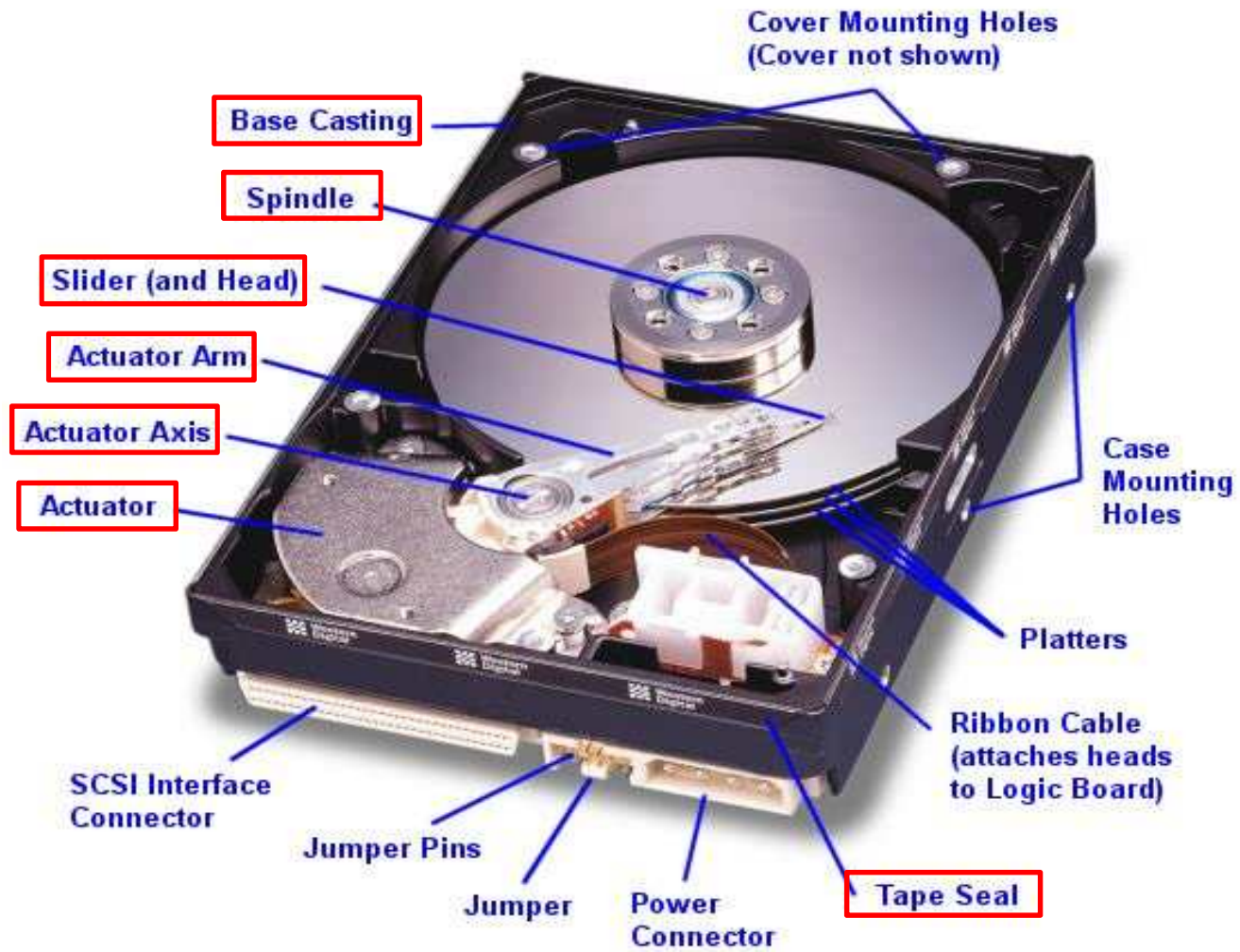
# Technology Differences

## • Mechanics - major components



# Technology Differences

## • Mechanics – Head/Disc Assembly





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# Technology Differences

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## • Mechanics – Head/Disc Assembly (ES)

- ✓ Head/Disk Assembly(HDA) – heads, actuator, spindle, discs, air handling system
- ✓ ES drives operates at higher rpm
  - maintaining a higher tolerance for **external disturbance**
  - require **more power** to operate, creating **more heat**
  - In the event, can be the **influence of neighboring drives**
- ✓ To prevent :
  - **filter for particles, desiccant to control humidity, eliminating organic**
  - **O-ring seals, better gasketing, air control system**
- ✓ These little things adds cost but improves reliability

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# Technology Differences

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## • Mechanics – Head/Disc Assembly (PS)

- ✓ PS drives are designed for reliability
- ✓ But they tend to compromise where components can be eliminated to save cost
- ✓ The O-rings and desiccant, for example, are usually eliminated in PS drives

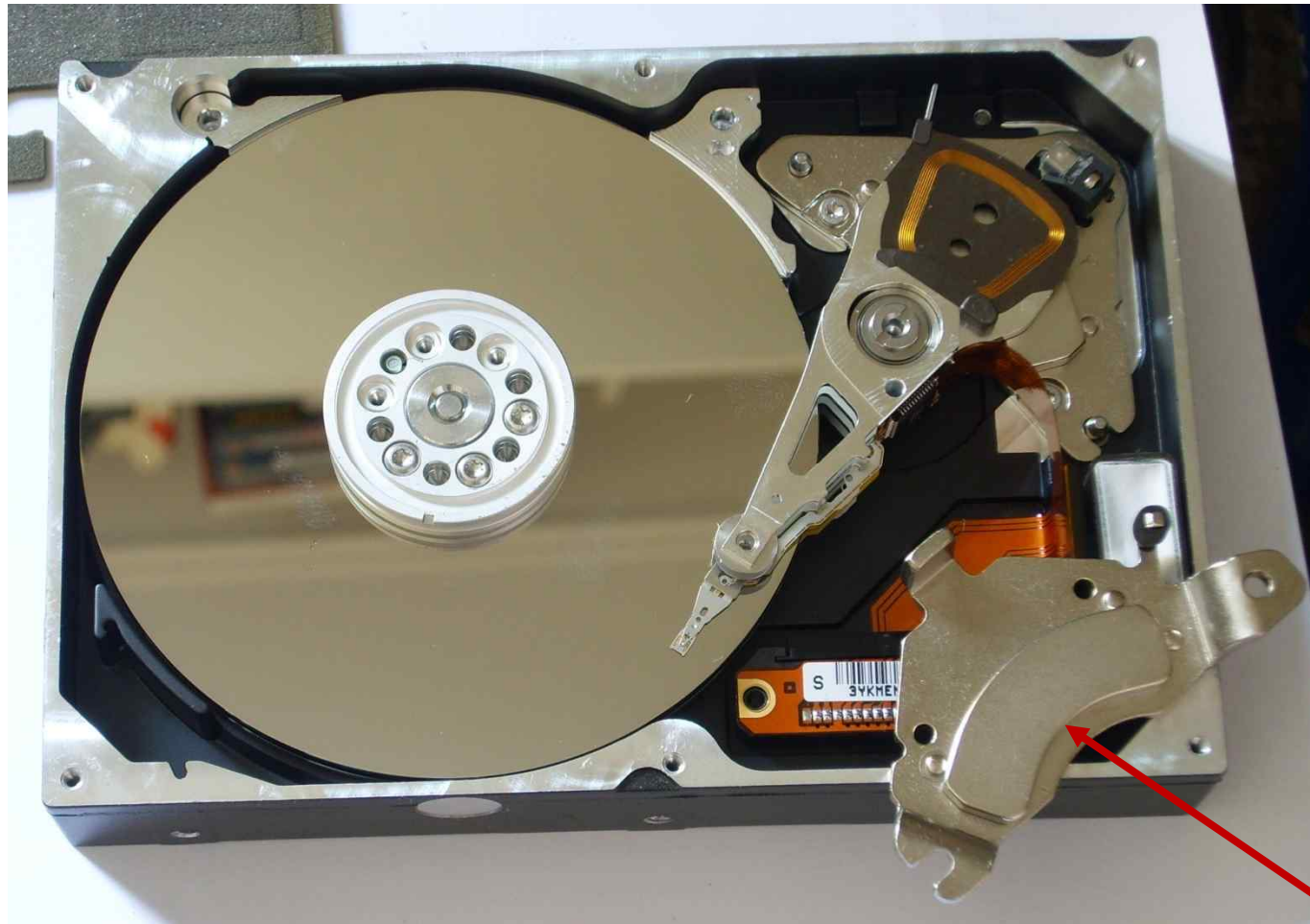
# Technology Differences

## • Mechanics – Actuator



# Technology Differences

## • Mechanics – Actuator



Magnet Actuator

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# Technology Differences

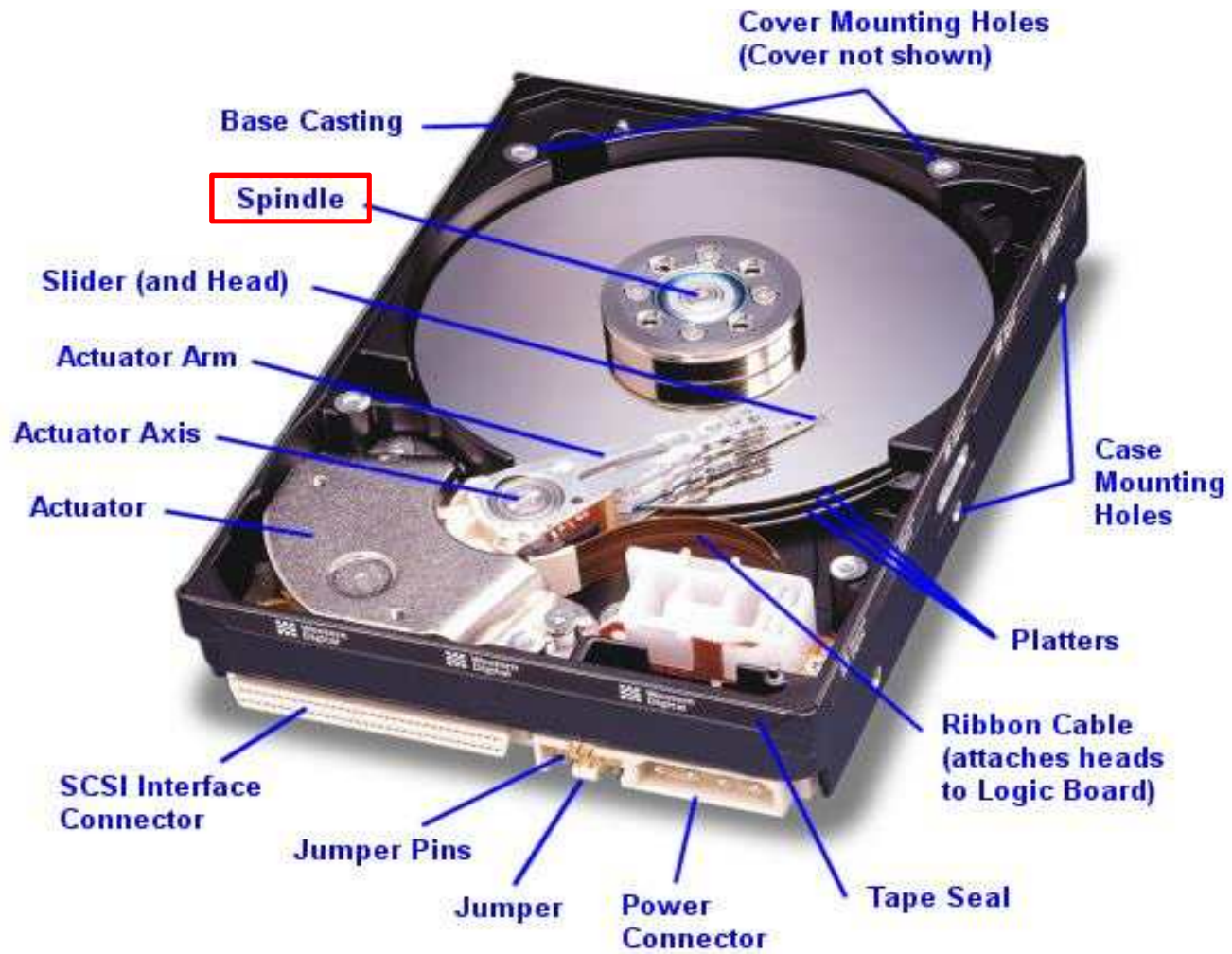
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## • Mechanics – Actuator

- ✓ Larger magnets are key to achieving faster seek times → higher cost
- ✓ Inside every drive is a latch to hold the actuator when power is off
- ✓ The latch has a magnetic field associated with it, affect seek performance when the actuator is operating near the latch
- ✓ In PS drive, no compensation for this, as seek performance is not critical
- ✓ ES drives have a bi-stable latch that does not affect performance

# Technology Differences

## • Mechanics – Spindle



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# Technology Differences

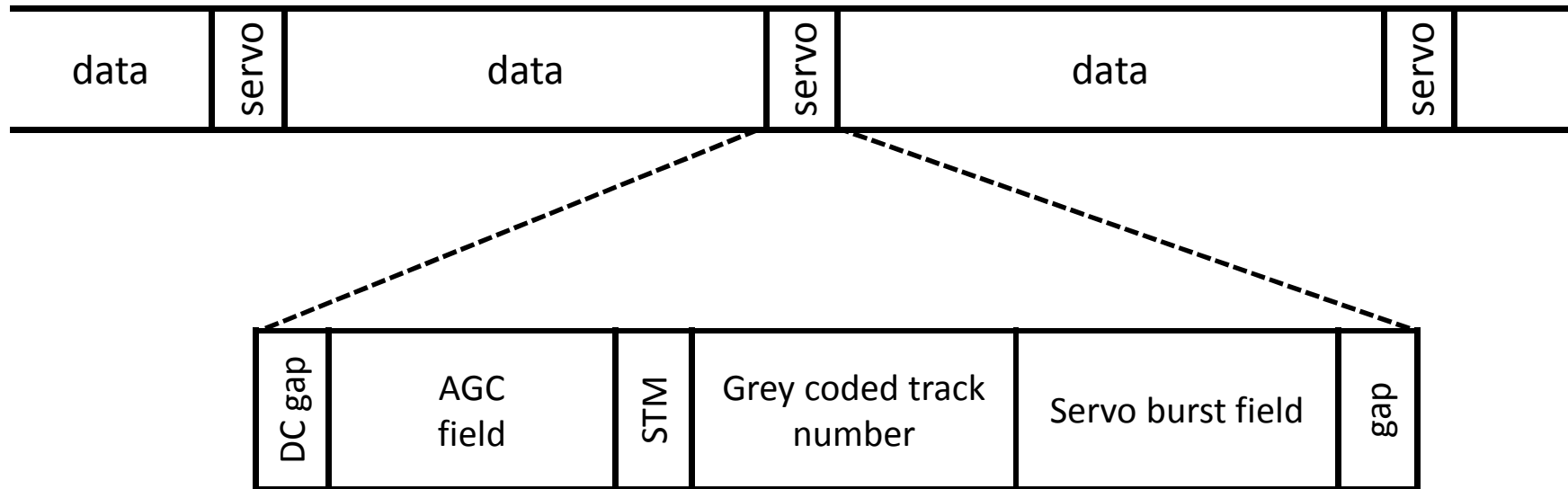
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## • Mechanics – Spindle

- ✓ For over 15 years drives spun **no faster than 3,600 rpm**
- ✓ 3,600 rpm → 5,400 rpm → 7,200 rpm → 10,000 rpm → 15,000 rpm
- ✓ Higher rpm → Off-track head → *mis-read and a rotational miss*
- ✓ Higher rpm requires **more expensive motors, windage, and vibration**
- ✓ PS drives use a cantilever motor design, **only at the base deck end**
- ✓ ES motor **at both ends**, with an attachment to the top cover → cost extra

# Technology Differences

## • Electronics – Servo processor





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# Technology Differences

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## • Electronics – Interface

- ✓ ES drive characteristic
  - the ES ASIC gate count is **more than 2x** a PS drive
  - the embedded SRAM space for **program code is 2x**
  - the permanent flash memory for **program code is 2x**
  - data SRAM and cache SRAM space is **more than 10x**
  
- ✓ ES drive - **two processors**
  - one dedicated to servo
  - other for interface and read/write handling
  
- ✓ PS drive – **single processor**
  - handle all three basic processor tasks (interface, read/write, servo processing)

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# Technology Differences

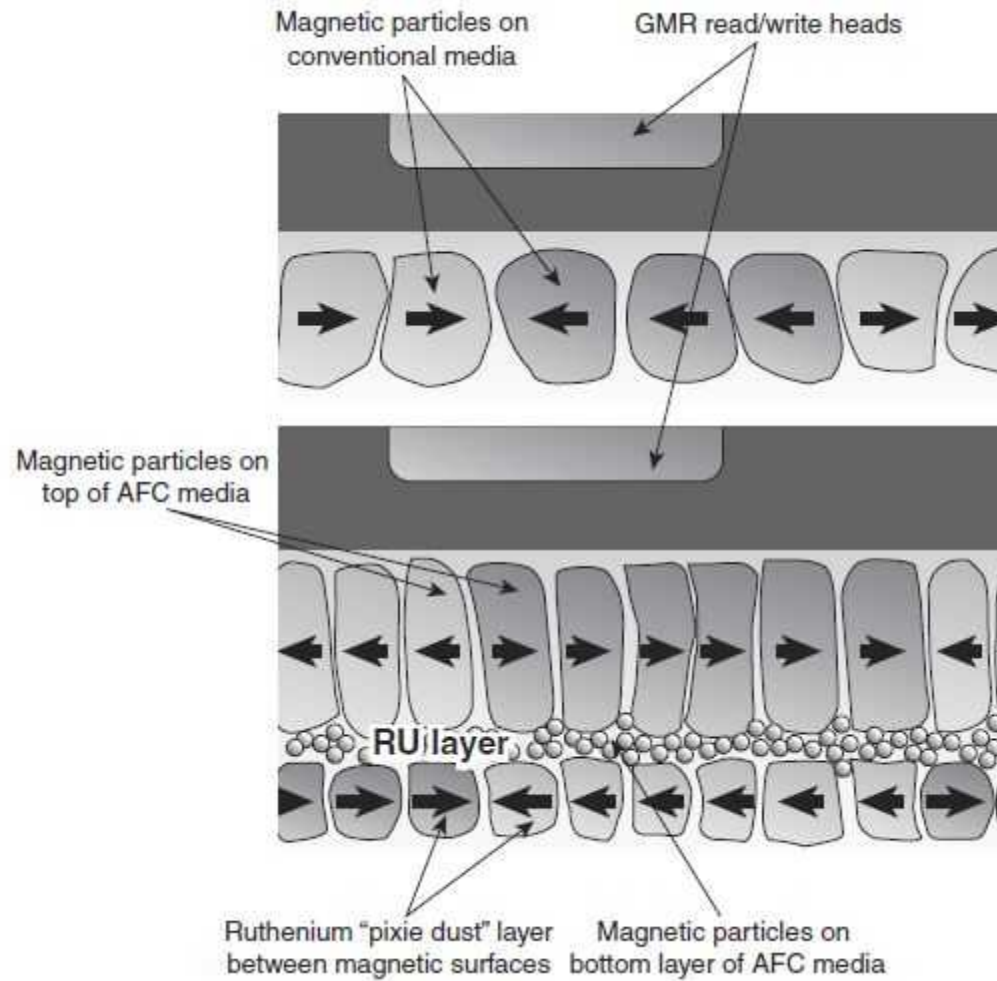
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## • Electronics – Memory

- ✓ ES command set is **more than twice as large as that for ATA**
- ✓ requiring **more permanent flash** for code and increased SRAM at runtime
- ✓ allows for vendor-specific extensions which require **additional code space**
- ✓ allowing greater flexibility in configuration

# Technology Differences

## • Electronics – Materials



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# Technology Differences

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## • Electronics – Manufacturing

- ✓ The build and test times for ES drives are considerably longer than PS drives
- ✓ Increased test time → more reliable

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# Performance Differences

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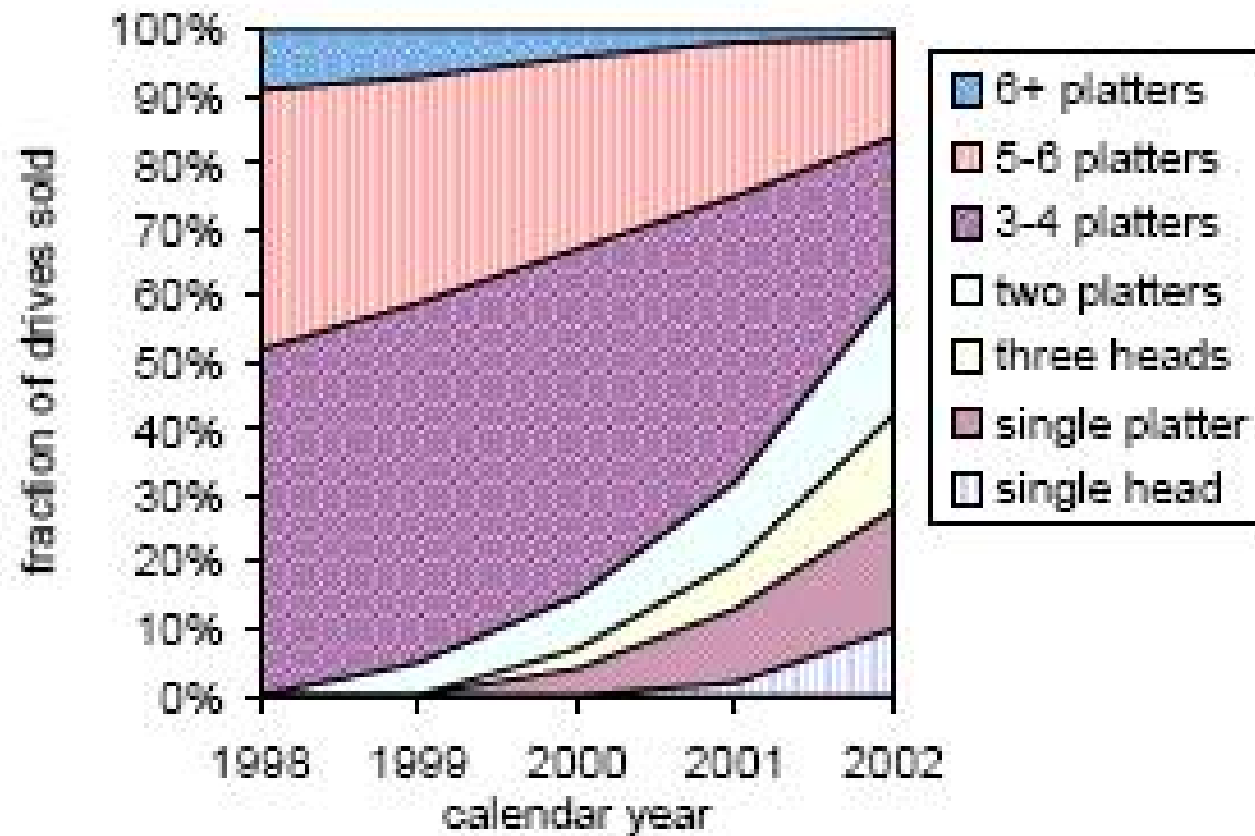
## • Capacity – Size of Platters

- ✓ 15,000 rpm drives use 2.5" platters to support the faster spindle speeds
- ✓ 7,200 rpm drives use 3.7" platters
- ✓ ES drive uses more platters to achieve the same capacity as a PS drive
- ✓ The smaller platters two performance advantages :
  - ability to spin faster and faster seeking
  - random access much faster than PS drive

# Performance Differences

## • Capacity – Number of Platters

- ✓ Fewer platters have less heads → faster seeks



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# Performance Differences

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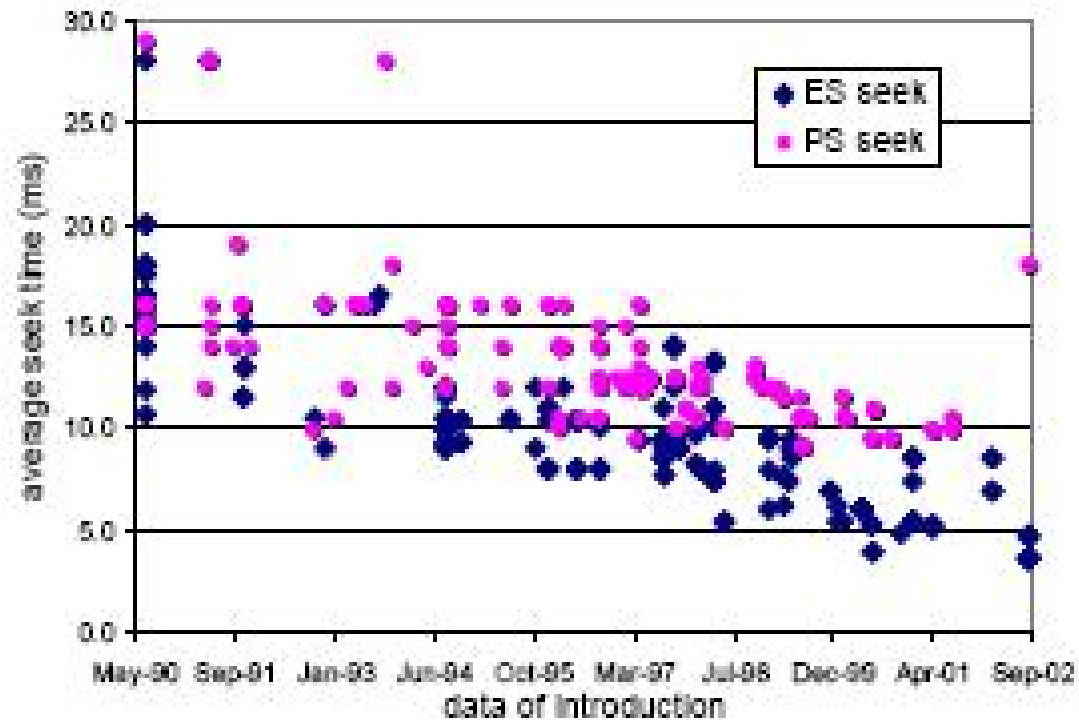
## • Capacity – Data rate

- ✓ ES drives have higher data rate than a PS drive
- ✓ However, PS drive has an advantage in media size
  - ✓ PS drive : 80 mm (3.3"), 95 mm (3.7") platters in 10,000 rpm
  - ✓ ES drive : 65 mm (2.5") platter in 15,000 rpm
- ✓ The larger media size helps the PS drives follow closely in data rate

# Performance Differences

## • Random performance – Seek times

- ✓ Seek performance of PS drives always lags that of ES drives





# Performance Differences

## • Random performance – Seek times

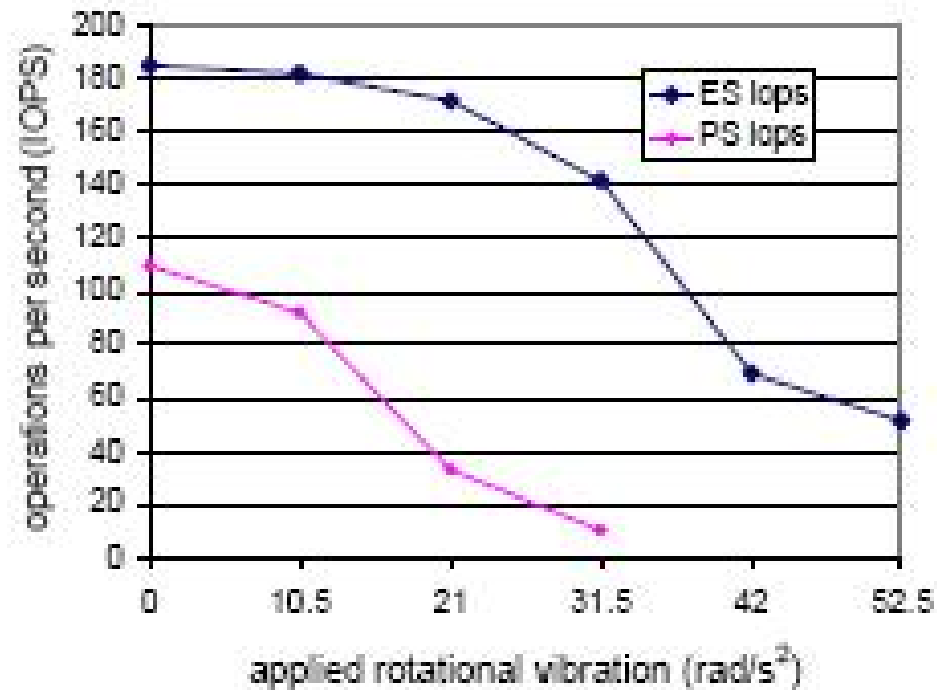
- ✓ ES drive is focused on achieving the highest **random access performance**

queue depth	read (8 KB)		write (8 KB)	
	PS	ES	PS	ES
1 requests	65 req/s	115 req/s	105 req/s	184 req/s
2 requests	66 req/s	116 req/s	105 req/s	184 req/s
4 requests	71 req/s	146 req/s	105 req/s	187 req/s
8 requests	79 req/s	174 req/s	105 req/s	190 req/s
16 requests	89 req/s	202 req/s	108 req/s	200 req/s
32 requests	101 req/s	235 req/s	108 req/s	213 req/s

# Performance Differences

## • Random performance – Rotational vibration

- ✓ Since PS drives are built to be in **single drive systems** → not an important factor
- ✓ ES drives are designed to operate in cabinets full of spinning drives



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# Performance Differences

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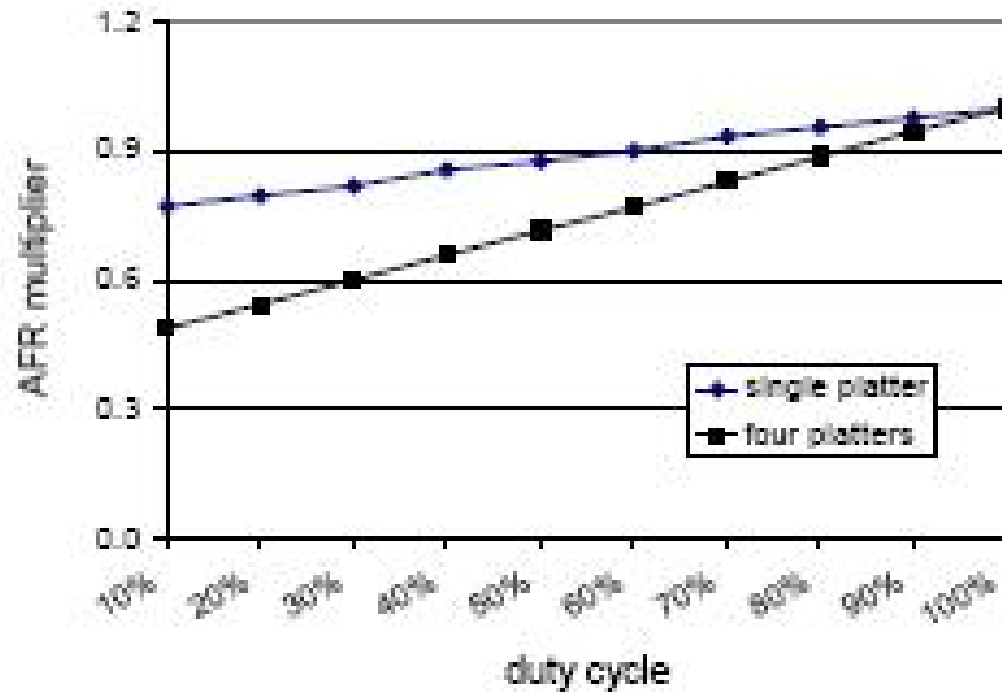
## • Reliability

- ✓ MTBF
  - ✓ PS drives : 8 hours/day for 300 days/year
  - ✓ ES drives : 24 hours/day for 365 days/year

# Performance Differences

## • Reliability – Duty cycle

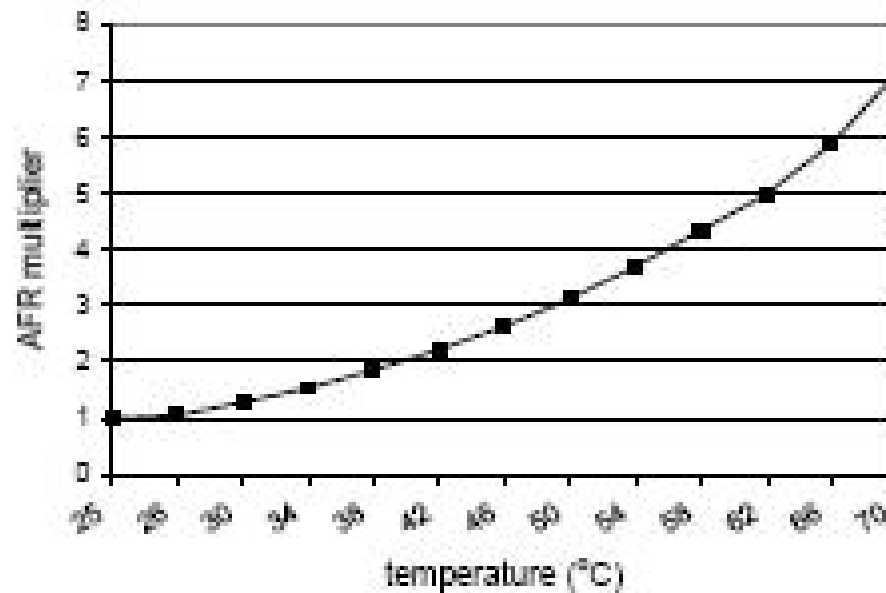
- ✓ Reliability is decreased with higher duty cycle
- ✓ The effect is greater for drives with larger numbers of platters



# Performance Differences

## • Reliability – Temperature

- ✓ Reliability decreases with increases in ambient temperature
- ✓ To prevent contain temperature sensors



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# Performance Differences

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## • Reliability – Overall reliability

- ✓ Reported a failure rate[Talagala99] :
  - ✓ 25 % for 24 IDE drives
  - ✓ 2 % for 368 SCSI drives

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# Summary and Discussion

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## • Summary

- ✓ **Data rate** is proportional to spindle speed, areal density, and platter size
- ✓ **Fast seeks** more and target the enterprise market (cost extra)
  - include large magnets, better bearings, and stiffer actuators
- ✓ **Protection from rotational vibration** (cost extra)
  - includes better motors, top covers, stiffer actuators
- ✓ **Better scheduling** (cost extra)
  - requiring more code space, more memory for re-order queues or algorithm

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# Summary and Discussion

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## • Summary

- ✓ **Interface electronics** (cost extra)
  - more customer-modifiable options and host connectivity
- ✓ As a result, **High reliability requires cost extra**



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# Conclusions

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## • ATA vs. SCSI

- ✓ They derive from the different requirements of the respective markets
  - ✓ PS drive : lower cost
  - ✓ ES drive : faster random access

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# Question and Answer

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